SI Session: Final Exam Review Saturday, December 6th : 2:00 PM – 4:00 PM Monday, December 8th: 3:00 PM – 4:30 PM Room 1239 SNAD

Prof. McCurdy : Linear Algebra Fall 2008 SI Leader : Neil Jody

[1] Solve the following system.
$$\begin{cases} x_1 + 3x_2 - 2x_3 = 10\\ 2x_1 + 3x_2 + 5x_3 = -1\\ -x_1 + 2x_2 + 4x_3 = -9 \end{cases}$$



[3] Consider the linear transformation $T: \xrightarrow{3} \rightarrow \xrightarrow{3}$ defined by $T(\vec{x}) = \begin{bmatrix} 2 & 3 & 1 \\ 1 & 4 & -2 \\ 1 & 2 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}. \text{ Let } \vec{u} = \begin{bmatrix} -2 \\ -1 \\ 5 \end{bmatrix}$

(a) Find the image of T under \vec{u}

(b) Is \vec{u} in the range of T?

[4] Suppose that the RREF of a matrix A is
$$\begin{bmatrix} 1 & 0 & -2 & 0 & 4 \\ 0 & 1 & 3 & 0 & -1 \\ 0 & 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$
.

Write the solution set of the equation $A\vec{x} = \vec{0}$ in parametric vector form.



[6] Do the vectors
$$\begin{bmatrix} 2\\1\\3 \end{bmatrix}, \begin{bmatrix} 4\\-1\\2 \end{bmatrix}, \begin{bmatrix} 2\\4\\7 \end{bmatrix}$$
, and $\begin{bmatrix} 1\\1\\-8 \end{bmatrix}$ span ³. (Justify your answer.)

[7] Consider the linear transformation $T: {}^2 \rightarrow {}^3$ defined by

$$T\left(\vec{x}\right) = \begin{bmatrix} 1 & 4 \\ 2 & 3 \\ 1 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}.$$

(a) Is T one-to-one?
(b) Is T onto?
(Justify your answer.)

[8] Let
$$A = \begin{bmatrix} 0 & 2 & 5 \\ 1 & 1 & 2 \\ 2 & 3 & 6 \end{bmatrix}$$
.

(a) Calculate $2A + A^T$.

(b) Calculate A^{-1} .

[9] Let
$$T: {}^{3} \rightarrow {}^{2}$$
 be defined by $T\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}\right) = \begin{bmatrix} x-z \\ 2y \end{bmatrix}$. Show that T is a linear transformation.

[10] Let
$$S = \{(a,b,2a+b) | a,b \in \}$$
. Prove that S is a subspace of ³.

[11] Let *S* be a set of all ordered pairs
$$\begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$
 with vector addition defined by
 $\begin{bmatrix} u_1 \\ u_2 \end{bmatrix} + \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} u_2 + v_2 \\ u_1 + v_1 \end{bmatrix}$ and scalar multiplication defined by $c \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} cu_1 \\ u_2 \end{bmatrix}$.

Determine whether S satisfies Axiom 8 : $(c+d)\vec{u} = c\vec{u} + d\vec{u}$

[12] Decide whether the polynomials $p_1 = x^2 - 2x + 3$, $p_2 = 2x^2 - 5x + 2$, and $p_3 = 2x^2 - 3x + 10$ are linearly independent in P_2 .

- [13] Suppose A is a 3×5 matrix, and the column space of A is 2-dimensional.
 - (a) What is the rank of A?
 - (b) What is the dimension of the row space of A?
 - (c) What is the dimension of the null space of A?
 - (d) What is the dimension of the null space of A^T ?
 - (e) Is the row space of A a subspace of 3 or 5 ?

[14] Consider the vectors
$$\vec{v}_1 = \begin{bmatrix} 1 \\ -3 \\ 4 \\ 0 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} -2 \\ 6 \\ -8 \\ 0 \end{bmatrix}, \vec{v}_3 = \begin{bmatrix} 3 \\ 2 \\ -5 \\ 1 \end{bmatrix}, \vec{v}_4 = \begin{bmatrix} 5 \\ -4 \\ 3 \\ 1 \end{bmatrix}.$$

Let $V = \text{span}\{\vec{v}_1, \vec{v}_2, \vec{v}_3, \vec{v}_4\}$
(a) Find a basis for V .

(b) What is the dimension of V?

(c) Is
$$\vec{w} = \begin{bmatrix} 1 \\ -25 \\ 38 \\ -2 \end{bmatrix}$$
 a vector in $V = \text{span}\{\vec{v}_1, \vec{v}_2, \vec{v}_3, \vec{v}_4\}$?

[15] Let
$$A = \begin{bmatrix} 0 & 1 & 2 & 1 \\ 1 & 0 & 3 & 1 \\ 1 & 1 & 5 & 2 \end{bmatrix}$$
. Find a basis for the column space of A .

[16] Find the characteristic polynomial, eigenvalues, and a basis for each eigenspace $\begin{bmatrix} 4 & 2 \end{bmatrix}$

for
$$A = \begin{bmatrix} 1 & 2 \\ 2 & 7 \end{bmatrix}$$
.

[17] Find the determinant of
$$\begin{bmatrix} 8 & 3 & 0 & 5 \\ 5 & 3 & 1 & -2 \\ 2 & 2 & 0 & 5 \\ 12 & 6 & 2 & -4 \end{bmatrix}.$$

[18] Consider the vectors
$$\vec{v}_1 = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$$
, $\vec{v}_2 = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}$, $\vec{v}_3 = \begin{bmatrix} -5 \\ -2 \\ 1 \end{bmatrix}$.

(a) Verify that the vectors form an orthogonal set.

(b) Write the vector
$$\vec{w} = \begin{bmatrix} -14 \\ -6 \\ 8 \end{bmatrix}$$
 as a linear combination of \vec{v}_1 , \vec{v}_2 , and \vec{v}_3 .

[19] Diagonalize the matrix
$$A = \begin{bmatrix} 2 & 1 & 2 \\ 0 & 3 & 2 \\ 0 & 1 & 4 \end{bmatrix}$$
 (if possible).