SI Session: Exam I Review
Mondays: 3:00 PM – 4:30 PM
Tuesdays: 1:30 PM – 3:00 PM
Thursdays: 1:30 PM – 3:00 PM
Room 1239 SNAD

Prof. McCurdy : Linear Algebra Fall 2008 SI Leader : Neil Jody

[1] Solve the following system.
$$\begin{cases} x_1 + 3x_2 - 2x_3 = 10\\ 2x_1 + 3x_2 + 5x_3 = -1\\ -x_1 + 2x_2 + 4x_3 = -9 \end{cases}$$



[3] Consider the linear transformation $T: \xrightarrow{3} \rightarrow \xrightarrow{3}$ defined by $T(\vec{x}) = \begin{bmatrix} 2 & 3 & 1 \\ 1 & 4 & -2 \\ 1 & 2 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}. \text{ Let } \vec{u} = \begin{bmatrix} -2 \\ -1 \\ 5 \end{bmatrix}$

(a) Find the image of T under \vec{u}

(b) Is \vec{u} in the range of T?

[4] Suppose that the RREF of a matrix A is
$$\begin{bmatrix} 1 & 0 & -2 & 0 & 4 \\ 0 & 1 & 3 & 0 & -1 \\ 0 & 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$
.

Write the solution set of the equation $A\vec{x} = \vec{0}$ in parametric vector form.



[6] Do the vectors
$$\begin{bmatrix} 2\\1\\3 \end{bmatrix}, \begin{bmatrix} 4\\-1\\2 \end{bmatrix}, \begin{bmatrix} 2\\4\\7 \end{bmatrix}$$
, and $\begin{bmatrix} 1\\1\\-8 \end{bmatrix}$ span ³. (Justify your answer.)

[7] Consider the linear transformation $T: {}^2 \rightarrow {}^3$ defined by

$$T\left(\vec{x}\right) = \begin{bmatrix} 1 & 4\\ 2 & 3\\ 1 & 6 \end{bmatrix} \begin{bmatrix} x_1\\ x_2 \end{bmatrix}.$$

(a) Is T one-to-one?
(b) Is T onto?
(Justify your answer.)

[8] Let
$$\vec{x} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$
 and $\vec{y} = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$. Give an example of a nonzero vector which is in the

span of \vec{x} and \vec{y} .

[9] Find a value *c* so the system of equations $\begin{cases} x_1 + x_2 = 2\\ -3x_1 + cx_2 = -6 \text{ will be consistent.} \\ 2x_1 + x_2 = 7 \end{cases}$

[10] Describe geometrically what each transformation does to a vector in R^2 .

(a)
$$T\left(\begin{bmatrix} x_1\\ x_2 \end{bmatrix}\right) = \begin{bmatrix} 0 & -1\\ 1 & 0 \end{bmatrix} \begin{bmatrix} x_1\\ x_2 \end{bmatrix}$$
 (b) $T\left(\begin{bmatrix} x_1\\ x_2 \end{bmatrix}\right) = \begin{bmatrix} -3 & 0\\ 0 & -3 \end{bmatrix} \begin{bmatrix} x_1\\ x_2 \end{bmatrix}$